

Equivariant splittings of supermanifolds

Mitchell Rothstein

*Department of Mathematics, University of Georgia, Athens, GA 30602, USA*¹

Received 2 March 1992

(Revised 9 June 1992)

Let G be a group acting on a supermanifold (M, \mathcal{A}) . We ask whether (M, \mathcal{A}) is equivariantly isomorphic to the exterior sheaf of a vector bundle. When G is a Lie group and the underlying vector bundle of \mathcal{A} is G -homogeneous, the question can be reduced to a finite-dimensional group-cohomology calculation. In particular, we obtain a vanishing theorem for the obstruction to an equivariant isomorphism, in case the isotropy subgroup is compact or semisimple.

Keywords: supermanifolds, group cohomology

1991 MSC: 58A50

PACS: 0240

1. Let M be a C^∞ manifold and $\mathcal{E} \rightarrow M$ a locally free sheaf of C_M^∞ -modules, i.e., the sheaf of sections of a smooth vector bundle. Then $\wedge \mathcal{E} \rightarrow M$ is a sheaf of supercommutative \mathbb{R} -algebras, in fact, a supermanifold. It is well known that every C^∞ supermanifold is of this form [B]. On the other hand, let $\text{Aut}(\wedge \mathcal{E})$ be the group of automorphisms of $\wedge \mathcal{E}$. By definition, an element of $\text{Aut}(\wedge \mathcal{E})$ is a diffeomorphism $M \xrightarrow{\phi_{\text{red}}} M$ together with an isomorphism $\phi_{\text{red}}^{-1}(\wedge \mathcal{E}) \xrightarrow{\phi^*} \wedge \mathcal{E}$ of sheaves, respecting the \mathbb{Z}_2 -graded \mathbb{R} -algebra structure. One similarly defines $\text{Aut}(\mathcal{E})$ to be the group whose elements are pairs $M \xrightarrow{\phi_{\text{red}}} M$ together with an isomorphism $\phi_{\text{red}}^{-1}(\mathcal{E}) \xrightarrow{\phi^*} \mathcal{E}$ of sheaves, respecting the C_M^∞ -module structure. There is an obvious injection $\text{Aut}(\mathcal{E}) \hookrightarrow \text{Aut}(\wedge \mathcal{E})$ associating to any $\phi \in \text{Aut}(\mathcal{E})$ the unique element of $\text{Aut}(\wedge \mathcal{E})$ which extends ϕ and preserves the \mathbb{Z} -grading of $\wedge \mathcal{E}$. In fact the image of ι consists precisely of those automorphisms which preserve the \mathbb{Z} -grading. There are additional automorphisms of $\wedge \mathcal{E}$ obtained as follows. Let $\text{Der}(\wedge \mathcal{E})$ denote the Lie superalgebra of derivations of $\wedge \mathcal{E}$. By definition, an element of $\text{Der}(\wedge \mathcal{E})$ is a function associating to each open set $U \subset M$ a superderivation of $\wedge \mathcal{E}(U)$. Then let $\text{Der}^+(\wedge \mathcal{E})$ denote the Lie subalgebra of $\text{Der}(\wedge \mathcal{E})$ consisting of those

¹ E-mail: rothstei@joe.math.uga.edu

derivations which increase degree and preserve the \mathbb{Z}_2 -grading. For any $Y \in \text{Der}^+(\wedge \mathcal{E})$, e^Y is well defined as a polynomial in Y , so we obtain a subgroup $N(\wedge \mathcal{E}) = \exp(\text{Der}^+(\wedge \mathcal{E})) \subset \text{Aut}(\wedge \mathcal{E})$. The image of ι intersects $N(\wedge \mathcal{E})$ trivially. In fact we have

Theorem 1 (cf. ref. [R]). *There is an exact sequence*

$$N(\wedge \mathcal{E}) \twoheadrightarrow \text{Aut}(\wedge \mathcal{E}) \twoheadrightarrow \text{Aut}(\mathcal{E}), \quad \phi \rightsquigarrow \tilde{\phi},$$

defined by the formulas $\tilde{\phi}_{\text{red}} = \phi_{\text{red}}$, $\tilde{\phi}^*(\alpha) \equiv \phi^*(\alpha) \pmod{\mathcal{N}^2}$. Since ι splits this sequence, we have

$$\text{Aut}(\wedge \mathcal{E}) = \text{Aut}(\mathcal{E}) \ltimes N(\wedge \mathcal{E}).$$

Proof. The map $\phi \rightsquigarrow \tilde{\phi}$ is clearly surjective, provided it is well defined. For this it suffices to show that for all $\phi \in \text{Aut}(\wedge \mathcal{E})$ and all $f \in C_M^\infty = \wedge^0 \mathcal{E}$, $(\phi^*(f))_0 = f \circ \phi_{\text{red}}$, where $(\phi^*(f))_0$ is the degree-0 component of $\phi^*(f)$. But for all $p \in M$, the map $C_M^\infty|_{\phi(p)} \rightarrow \mathbb{R}$, $f \rightsquigarrow (\phi^*(f))_0(p)$, defines an \mathbb{R} -linear homomorphism, and there is only one such, namely $f \rightsquigarrow f(\phi(p))$. Now suppose $\phi \in \text{Aut}(\wedge \mathcal{E})$ and $\tilde{\phi}$ is trivial. We must show that $\phi \in N(\wedge \mathcal{E})$. Since $1 - \phi$ induces the identity on $\wedge \mathcal{E}/\mathcal{N}^2$, and since ϕ is an automorphism, it follows that $1 - \phi$ is degree increasing. Then we may define $Y = \log(\phi) = -\sum (1 - \phi)^n/n$, the sum being finite. Then $Y \in \text{Der}^+(\wedge \mathcal{E})$ and $\phi = e^Y$. □

Now let G be a group acting on $\wedge \mathcal{E}$. I.e., consider a homomorphism $G \xrightarrow{T} \text{Aut}(\wedge \mathcal{E})$. We get a homomorphism $G \xrightarrow{\tilde{T}} \text{Aut}(\mathcal{E})$, $\tilde{T}(g) = \widetilde{T(g)}$. On the other hand, the inclusion $\text{Aut}(\mathcal{E}) \twoheadrightarrow \text{Aut}(\wedge \mathcal{E})$ allows us to regard \tilde{T} as another action of G on $\wedge \mathcal{E}$ (which we continue to call \tilde{T}). The *equivariant* splitting problem is to determine whether T and \tilde{T} are equivalent, in the sense that they are intertwined by conjugation by some element of $\text{Aut}(\wedge \mathcal{E})$. The source of this terminology is the following. The short exact sequence

$$0 \rightarrow \mathcal{N}^2 \rightarrow \wedge \mathcal{E} \rightarrow \mathcal{E} \oplus C_M^\infty \rightarrow 0 \tag{*}$$

is $\text{Aut}(\wedge \mathcal{E})$ -equivariant, and therefore G -equivariant. Then T and \tilde{T} are equivalent if and only if $(*)$ splits G -equivariantly as a sequence of sheaves of \mathbb{Z}_2 -graded algebras. Note also that $(*)$ splits equivariantly if and only if the \mathbb{Z} -grading on $\wedge \mathcal{E}$ can be redefined in such a way that it is preserved by G . Indeed, \tilde{T} certainly preserves the standard \mathbb{Z} -grading, which gives one direction of this assertion. Conversely, if $\bigoplus_{i=0}^{k_\mathcal{E}} \mathcal{A}_i$ is a \mathbb{Z} -grading preserved by $T(G)$, then $(*)$ gives $\mathcal{A}_0 \oplus \mathcal{A}_1 \approx C_M^\infty \oplus \mathcal{E}$. The inverse of this isomorphism extends to an automorphism $\phi \in \text{Aut}(\wedge \mathcal{E})$. Then ϕ intertwines T and \tilde{T} . Note that ϕ necessarily belongs to $N(\wedge \mathcal{E})$. Another way of thinking about the equivariant splitting problem is to imagine the supermanifold (M, \mathcal{A}) given without an explicit isomorphism with

$\wedge \mathcal{E}$, but with a group action. Then we are asking whether \mathcal{A} and $\wedge \mathcal{E}$ are G -equivariantly isomorphic.

We will solve the equivariant splitting problem in the case that G is a Lie group, $M = G/H$ for some closed subgroup H , and \mathcal{E} is the sheaf of sections $G \times_H V$ for some finite-dimensional H -module V . By solving we mean that the problem will be reduced to a calculation in the first cohomology group of H with coefficients in an appropriate *finite-dimensional* H -module W . The reduction is accomplished by means of Shapiro's lemma [BW], which asserts the equality of the H -cohomology groups of W and the G -cohomology groups of $\text{Ind}_H^G(W)$.

2. We begin by translating the question of equivariant splitting into a cohomology problem. Let $r = \text{rank}(\mathcal{E})$. For each $g \in G$, we may use theorem 1 to define $Y(g) \in \text{Der}^+(\wedge \mathcal{E})$ by $T(g) = e^{Y(g)} \tilde{T}(g)$. For any integer $j \leq r$, let $\text{Der}^j(\wedge \mathcal{E})$ denote the j th graded piece of $\text{Der}(\wedge \mathcal{E})$, and let $Y_j(g)$ denote the piece of $Y(g)$ belonging to $\text{Der}^j(\wedge \mathcal{E})$. Let us say $Y(g)$ vanishes to order j if $Y_k(g) = 0$ for all $k \leq j$. If we conjugate T by some element $e^Z \in N(\wedge \mathcal{E})$, it may be possible to increase the order of Y . We define the order of T to be the supremum of integers $j \leq r$ such that there exists $Z \in \text{Der}^+(\wedge \mathcal{E})$ such that for all $g \in G$, $e^Z T(g) e^{-Z} = e^{Y'(g)} \tilde{T}(g)$, where $Y'(g)$ vanishes to order j . Clearly, T and \tilde{T} are equivalent if and only if T has order r . Suppose then that T has order j , and assume, after conjugating T appropriately, that for all $g \in G$, Y vanishes to order j . Then set $Y(g) = Y_{j+1}(g) + \text{higher order terms}$.

Theorem 2. *The function $g \rightsquigarrow Y_{j+1}(g)$ is a cocycle with respect to the adjoint action of $\tilde{T}(G)$ on $\text{Der}^{j+1}(\wedge \mathcal{E})$, i.e.,*

$$Y_{j+1}(gh) = Y_{j+1}(g) + \tilde{T}(g) Y_{j+1}(h) \tilde{T}(g^{-1}) .$$

Its cohomology class is an invariant of T , and is non-zero if and only if T and \tilde{T} are equivalent.

Proof. For all $g, h \in G$,

$$(1 + Y_{j+1}(g)) \tilde{T}(g) (1 + Y_{j+1}(h)) \tilde{T}(h) \equiv (1 + Y_{j+1}(gh)) \tilde{T}(gh)$$

modulo terms of order $j+2$. That is,

$$Y_{j+1}(g) \tilde{T}(gh) + \tilde{T}(g) Y_{j+1}(h) \tilde{T}(h) = Y_{j+1}(gh) \tilde{T}(gh) ,$$

or equivalently,

$$Y_{j+1}(gh) = Y_{j+1}(g) + \tilde{T}(g) Y_{j+1}(h) \tilde{T}(g^{-1}) .$$

This proves the first assertion. Now suppose we conjugate T by an element of $\phi \in N(\wedge \mathcal{E})$ in such a way that for all $g \in G$, the order of $Y(g)$ does not decrease. We may write ϕ in the form $e^{Z_1 \dots e^{Z_2}}, e^{Z_k} \in \text{Der}^k(\wedge \mathcal{E})$. It follows by induction on

k that Z_k commutes with $\tilde{T}(g)$ for $k \leq j$, and therefore $Y_{j+1}(g)$ changes by

$$Y_{j+1}(g) \rightsquigarrow Y_{j+1}(g) + Z_{j+1} - \tilde{T}(g)Z_{j+1}\tilde{T}(g^{-1}),$$

i.e., by a coboundary. This proves the second assertion. The third assertion follows from the very definition of Y_{j+1} . □

3. Specialize now to the case described in section 1: G is a real analytic group, H is a closed subgroup, $M = G/H$, $H \rightarrow \rho \text{GL}(V)$ is a finite-dimensional representation of H , and \mathcal{E} is the sheaf of C^∞ sections of the homogeneous vector bundle $G \times_\rho V$. Let \mathfrak{h} denote the Lie algebra of H , and $\dot{\rho}: \mathfrak{h} \rightarrow \text{End}(V)$ the derivative of ρ . Then we have $\text{graph}(\dot{\rho}) \subset \text{End } V \oplus \mathfrak{h}$. Each element of $\text{End } V$ extends to derivation of $\wedge V$, so $\text{graph}(\dot{\rho})$ may be regarded as an H -submodule of $\text{Der}(\wedge V) \oplus \mathfrak{g}$, with H acting on \mathfrak{g} by Ad. Note that $\text{Der}(\wedge V) = \wedge V \otimes V^*$. Let $\langle \text{graph}(\dot{\rho}) \rangle$ denote the $\wedge V$ -submodule of $\wedge V \otimes (V^* \oplus \mathfrak{g})$ generated by $\text{graph}(\dot{\rho})$. Set $W = (\wedge V \otimes (V^* \oplus \mathfrak{g})) / \langle \text{graph}(\dot{\rho}) \rangle$.

Proposition 3. $\text{Der}(\wedge \mathcal{E}) = \text{Ind}_H^G(W)$, i.e. the space of sections of $G \times_H W$.

Proof. Clearly, sections of $G \times_H (\wedge V \otimes V^*)$ determine derivations of $\wedge \mathcal{E}$. So do sections of $G \times_H \mathfrak{g}$, for, if $\varphi: G \rightarrow \mathfrak{g}$ transforms under H by Ad and $f: G \rightarrow \wedge V$ transforms under H by ρ , then for all $a \in G$, define

$$\varphi f(a) = (d/dt)|_0 f(ae^{t\varphi(a)}).$$

Then for all $b \in H$,

$$\begin{aligned} \varphi f(ab) &= (d/dt)|_0 f(abe^{t\varphi(ab)}) \\ &= (d/dt)|_0 f(ae^{t\varphi(a)}b) \\ &= \rho(b^{-1})\varphi f(a). \end{aligned}$$

It is easy to see then that every derivation comes from a section of $G \times_H (\wedge V \otimes V^* \oplus \wedge V \otimes \mathfrak{g})$, and that the kernel is the space of sections of $G \times_H \langle \text{graph}(\dot{\rho}) \rangle$. □

Recall from ref. [HM] the notion of a differentiable G -module. If A is a real topological vector space, and also a G -module, then it is a *continuous* G -module if the map $G \times A \rightarrow A$, $(g, a) \rightsquigarrow ga$ is continuous. If, furthermore, for all $a \in A$, the map $G \rightarrow A$, $g \rightsquigarrow g \cdot a$ is an infinitely differentiable map, then A is called a *differentiable* G -module. If B is any real topological vector space whose points are separated by continuous linear functionals, then we get a differentiable G -module by putting a suitable topology on the space of all differentiable maps from G to B .

In particular, if U is any finite-dimensional H -module, and \mathcal{F} is the sheaf of C^∞ sections on $G \times_H U$, then $C^\infty(G) \otimes U$ is a differentiable G -module, and there-

fore so is the sub-module $\Gamma(M, \mathcal{F})$. Thus it makes sense to consider the differentiable cohomology groups, $H_d^*(G, \Gamma(M, \mathcal{F}))$. We can of course also consider the differentiable cohomology groups $H_d^*(H, U)$. We then have

Shapiro’s lemma. $H_d^*(G, \Gamma(M, \mathcal{F}))$ and $H_d^*(H, U)$ are canonically isomorphic.

Proof. For the details of the proof, see ref. [BW]. Since we will be using the isomorphism in degree 1 explicitly in the example below, we give a sketch of the construction. Make $C^\infty(G) \otimes U$ a $G \times H$ -module, letting G act by $l_g(f \otimes u)(g') = f(g^{-1}g') \otimes u$, and letting H act by $h(f \otimes u)(g) = f(gh) \otimes h \cdot u$. Then U consists precisely of the G -invariants, and $\Gamma(M, \mathcal{F})$ consists precisely of the H -invariants. Moreover, $C^\infty(G) \otimes U$ turns out to be acyclic for both G and H . Then Shapiro’s lemma follows from a standard spectral sequence argument. In degree 1, the isomorphism works as follows. Let $\omega \in H_d^1(H, U)$ be represented by a cocycle $c: H \rightarrow U$. Regarding c as a $C^\infty(G) \otimes U$ -valued cocycle, we may choose some $f \in C^\infty(G) \otimes U$ such that for all $h \in H$, $c(h) = h^*f - f$. Then regarding f as a zero-chain with respect to G , we take its coboundary, $\delta f(g)(g') = f(g^{-1}g') - f(g')$. Then the isomorphism $H_d^1(H, U) \approx H_d^1(G, \Gamma(M, \mathcal{F}))$ takes ω to the class of δf . \square

In combination with Shapiro’s lemma, theorem 2 implies

Theorem 4. *With the notation as above, assume the function $g \rightsquigarrow Y(g)$ is differentiable. Then we may canonically associate to T an integer $j \leq \text{Dim}(V)$ and a cohomology class $\omega \in H_d^1(H, W_{j+1})$, where W_{j+1} is the $(j+1)$ st component of W , such that ω vanishes if and only if $j = \text{Dim}(V)$ if and only if T and \tilde{T} are equivalent.* \square

By theorem 4, we can deduce the equivalence of T and \tilde{T} in many cases without any computation. For example,

Corollary 5. *With the same assumptions as in theorem 4, suppose in addition that H is compact or semisimple. Then T and \tilde{T} are equivalent.*

Proof. In this case, $H_d^1(H, U)$ vanishes for any finite-dimensional H -module U . For the convenience of the reader, we recall the proof of this well-known fact. If $c: H \rightarrow U$ is any cocycle, then let $M = U^* \oplus \mathbb{C}$ with the H -module structure

$$h \cdot (\alpha, z) = ((h^{-1})^* \alpha, \langle c(h), \alpha \rangle + z),$$

where \langle , \rangle denotes the pairing between U and U^* . The short exact sequence

$$0 \rightarrow \mathbb{C} \rightarrow M \rightarrow U^* \rightarrow 0$$

must split as a sequence of H -modules. This gives a linear map from U^* to \mathbb{C} , i.e. an element $u \in U$. Then c is the coboundary of u . \square

To produce a nonsplittable action of G , we must choose $H^1(H, W) \neq 0$. The easiest way to get an example is to find a class $\omega \in H^1(G, \text{Der}^j(\wedge \mathcal{E}))$ where $j > rk \mathcal{E} / 2$. Then if we represent ω by a cocycle $G \xrightarrow{\zeta} \text{Der}^j(\wedge \mathcal{E})$, we get a family of deformed actions of G :

$$g \rightsquigarrow \exp(t\zeta(g))l_g = (1 + t\zeta(g))l_g,$$

where we have written l_g to emphasize that initially g acts by the left regular representation on $\Gamma(M, \wedge \mathcal{E})$.

Example. Let

$$G = \text{SL}(2, \mathbb{R}), \quad N = \left\{ \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix} \middle| t \in \mathbb{R} \right\}.$$

Then $G/N = \mathbb{R}^2 - \{0\}$. Let E be the trivial bundle of rank 2 on G/N , with basis e_1, e_2 . Then elements of $\text{Der}^2(\wedge \mathcal{E})$ are of the form $e_1 \wedge e_2 Z$, where Z is simply a vector field on $\mathbb{R}^2 - \{0\}$. Let L denote the space of smooth vector fields on $\mathbb{R}^2 - \{0\}$. By Shapiro's lemma,

$$H_d^1(\text{SL}(2, \mathbb{R}), L) \approx H_d^1(N, \mathfrak{g}/\mathfrak{n}),$$

where \mathfrak{g} and \mathfrak{n} are the Lie algebras of G and N , respectively. Let us use this isomorphism to produce a nontrivial cocycle $\text{SL}(2, \mathbb{R}) \xrightarrow{Z} L$. Let

$$H = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad X = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad Y = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}.$$

If we take H, Y to represent a basis for $\mathfrak{g}/\mathfrak{n}$, we find that the action of N on $\mathfrak{g}/\mathfrak{n}$ is equivalent to its defining action on \mathbb{R}^2 . Identify N with \mathbb{R} . Thus a $\mathfrak{g}/\mathfrak{n}$ -valued cocycle becomes a smooth map

$$\mathbb{R} \xrightarrow{c} \mathbb{R}^2$$

such that for all $s, t \in \mathbb{R}$,

$$c(s+t) = c(s) + \begin{pmatrix} 1 & s \\ 0 & 1 \end{pmatrix} c(t).$$

Writing

$$c(s) = \begin{pmatrix} a(s) \\ b(s) \end{pmatrix},$$

we find that the general smooth solution is $b(s) = b_0 s, a(s) = a_0 s + \frac{1}{2} b_0 s^2$. Co-

boundaries are functions of the form

$$c(s) = v - \begin{pmatrix} 1 & s \\ 0 & 1 \end{pmatrix} v, \quad \text{for some } v \in \mathbb{R}^2,$$

i.e.,

$$c(s) = \begin{pmatrix} \lambda s \\ 0 \end{pmatrix}, \quad \lambda \in \mathbb{R}.$$

Therefore we may assume $a_0 = 0$, and thus $H_d^1(N, \mathfrak{g}/\mathfrak{n})$ is spanned by the cocycle $c(s) \equiv s^2 H + 2s Y \pmod{X}$. To trace through Shapiro's lemma, we must regard c as a cocycle with coefficients in $C^\infty(G) \otimes \mathfrak{g}/\mathfrak{n}$ and then find a function $W: G \rightarrow \mathfrak{g}/\mathfrak{n}$ such that c is the coboundary of W . The general element of G may be written

$$h = \begin{pmatrix} \lambda \cos \theta & s\lambda \cos \theta - \lambda^{-1} \sin \theta \\ \lambda \sin \theta & s\lambda \sin \theta + \lambda^{-1} \cos \theta \end{pmatrix} = h(\theta, \lambda, s).$$

Thus we may seek a W which depends only on s , and we readily find the solution $W(s) = s^2 H - 2s Y$. Indeed, for all s, t ,

$$\begin{pmatrix} t^2 \\ -2t \end{pmatrix} - \begin{pmatrix} 1 & s \\ 0 & 1 \end{pmatrix} \begin{pmatrix} (t+s)^2 \\ -2(t+s) \end{pmatrix} = \begin{pmatrix} t^2 - s^2 - 2st - t^2 + 2s^2 + 2st \\ -2t + 2s + 2t \end{pmatrix} = \begin{pmatrix} s^2 \\ 2s \end{pmatrix}.$$

Now let δW be the coboundary of W with respect to G . Thus, for all $g \in G$, $\delta W(g)$ is the function $\delta W(g): G \rightarrow \mathfrak{g}/\mathfrak{n}$ defined by

$$\delta W(g)(h) = W(s(h)) - W(s(g^{-1}h)).$$

We are to think of $\delta W(g)$ as a vector field on $\mathbb{R}^2 - \{0\}$. To write this out explicitly, first write the left invariant vector fields H_L and Y_L in terms of $\partial/\partial\theta$, $\partial/\partial\lambda$ and $\partial/\partial s$, and mod out the $\partial/\partial s$ term. The result is

$$H_L \equiv \lambda \frac{\partial}{\partial \lambda} \pmod{\frac{\partial}{\partial s}},$$

$$Y_L \equiv \frac{1}{\lambda^2} \frac{\partial}{\partial \theta} + s\lambda \frac{\partial}{\partial \lambda} \pmod{\frac{\partial}{\partial s}}.$$

Now define $\varphi_g(h) = s(h) - s(g^{-1}h)$. We now have

$$\delta W(g)(h) \equiv [s(h)^2 - s(g^{-1}h)^2] H_L - 2[s(h) - s(g^{-1}h)] Y_L \pmod{\partial/\partial s},$$

which yields

$$\begin{aligned}
\delta W(g)(h) &= [s(h)^2 - s(g^{-1}h)^2] \lambda \frac{\partial}{\partial \lambda} - 2[s(h) - s(g^{-1}h)] \left(s \lambda \frac{\partial}{\partial \lambda} + \frac{1}{\lambda^2} \frac{\partial}{\partial \theta} \right) \\
&= \varphi_g(\theta, \lambda) [s(h) + s(g^{-1}h)] \lambda \frac{\partial}{\partial \lambda} - 2\varphi_g(\theta, \lambda) \left(s(h) \lambda \frac{\partial}{\partial \lambda} + \frac{1}{\lambda^2} \frac{\partial}{\partial \theta} \right) \\
&= -\varphi_g(h)^2 \lambda \frac{\partial}{\partial \lambda} - 2\varphi_g(h) \frac{1}{\lambda^2} \frac{\partial}{\partial \theta}.
\end{aligned}$$

To be completely explicit, let us write out φ_g as a function of θ and λ . If $h = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$, then

$$s(h) = \frac{b}{a} + \frac{a}{c(a^2 + c^2)}.$$

Set

$$g^{-1} = \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix}.$$

If we assume, as we may, that $s(h) = 0$, then

$$\begin{aligned}
\varphi_g(\theta, \lambda) &= -s(g^{-1}h) \\
&= -s \left(\begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} \begin{pmatrix} \lambda \cos \theta & -\lambda^{-1} \sin \theta \\ \lambda \sin \theta & \lambda^{-1} \cos \theta \end{pmatrix} \right) \\
&= \frac{\alpha \lambda^{-1} \sin \theta - \beta \lambda^{-1} \cos \theta}{\alpha \lambda \cos \theta + \beta \lambda \sin \theta} - \frac{\gamma \lambda \cos \theta + \delta \lambda \sin \theta}{\alpha \lambda \cos \theta + \beta \lambda \sin \theta} \\
&\quad \times \frac{1}{(\alpha \lambda \cos \theta + \beta \lambda \sin \theta)^2 + (\gamma \lambda \cos \theta + \delta \lambda \sin \theta)^2}.
\end{aligned}$$

References

- [B] M. Batchelor, The structure of supermanifolds, *Trans. Am. Math. Soc.* 253 (1979) 329–338.
- [BW] A. Borel and N. Wallach, *Continuous Cohomology, Discrete Subgroups, and Representations of Reductive Groups*, *Annals of Math. Studies*, Vol. 94 (Princeton Univ. Press, Princeton, NJ, 1980).
- [HM] G. Hochschild and G.D. Mostow, *Cohomology of Lie groups*, *Ill. J. Math.* 6 (1962) 367–401.
- [R] M. Rothstein, Deformations of complex supermanifolds, *Proc. Am. Math. Soc.* 95 (1985) 255–260.